

**Matrices – Invariant Points and Lines Exam Questions (From OCR 4755)**

**Q1, (Jun 2006, Q5)**

|     |   |            |  |
|-----|---|------------|--|
| (i) | $\begin{pmatrix} -1 & 2 \\ -3 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ $S^{-1} = \frac{1}{2} \begin{pmatrix} 4 & -2 \\ 3 & -1 \end{pmatrix}$ $\frac{1}{2} \begin{pmatrix} 4 & -2 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ | B1         |  |
|     |   | M1,        | Attempt to divide by determinant and manipulate contents |
|     |   | A1         | Correct  |
|     |   | E1         |  |
|     |   | <b>[4]</b> |  |
| ii) | $T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$ $\Rightarrow T^{-1} T \begin{pmatrix} x \\ y \end{pmatrix} = T^{-1} \begin{pmatrix} x \\ y \end{pmatrix}$ $\Rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = T^{-1} \begin{pmatrix} x \\ y \end{pmatrix}$  | M1         | Pre-multiply by $T^{-1}$                                 |
|     |   | A1         | Invariance shown   |
|     |   | <b>[2]</b> |  |

**Q2, (Jun 2008, Q3)**

|  |  |            |  |
|--|--|------------|--|
|  | $\begin{pmatrix} -1 & -1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$ $\Rightarrow -x - y = x, \quad 2x + 2y = y$ $\Rightarrow y = -2x$ | M1         | For $\begin{pmatrix} -1 & -1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$ |
|  |  | M1         |  |
|  |  | B1         |  |
|  |  | <b>[3]</b> |  |

**Q3, (Jan 2005, Q9)**

|  |                           |   |
|--|---------------------------|---|
| (i) $\mathbf{M}^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbf{I}$   | B1<br>[1]                 |   |
| (ii) $\mathbf{M}^2$ gives the identity because a reflection, followed by a second reflection in the same mirror line will get you back where you started<br>OR reflection matrices are self-inverse.   | E1<br>[1]                 |   |
| (iii) $\begin{pmatrix} 0.8 & 0.6 \\ 0.8 & -0.6 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$<br><br>$\Rightarrow 0.8x + 0.6y = x$<br>and $0.6x - 0.8y = y$<br><br>Both of these lead to $y = \frac{1}{3}x$<br>as the equation of the mirror line. | M1<br>A1<br><br>A1<br>[3] | Give both marks for either equation or for a correct geometrical argument   |
| (iv) Rotation, centre origin, $36.9^\circ$ anticlockwise.  | B1, B1<br>[2]             | One for rotation and centre, one for angle and sense. Accept $323.1^\circ$ clockwise or radian equivalents (0.644 or 5.64). |
| (v) $\mathbf{MP} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$  | M1,<br>A1<br>[2]<br>B1    |   |
| (vi) $y = 0$   | [1]                       |   |

**Q4, (Jun 2005, Q3)**

$$\begin{pmatrix} 3 & -1 \\ 2 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} \Rightarrow x = 3x - y, y = 2x$$

$$\Rightarrow y = 2x$$

|           |   |
|-----------|---|
| M1<br>A1  | M1 for $\begin{pmatrix} 3 & -1 \\ 2 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$ (allow if implied)   |
| A1<br>[3] | $\begin{pmatrix} 3 & -1 \\ 2 & 0 \end{pmatrix} \begin{pmatrix} k \\ mk \end{pmatrix} = \begin{pmatrix} K \\ mK \end{pmatrix}$ can lead to full marks if correctly used. Lose second A1 if answer includes two lines |

**Q5, (OCR 2604, Jun 2001, Q4b)**

|   |   |  |  |
|---|---|--|--|
| (i)   | <p>(A)</p> $\begin{pmatrix} 4 & 2 \\ 6 & 4 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 4x + 2y \\ 6x + 4y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$ <p>The only invariant point is (0, 0)</p> <p>(B)</p> $\begin{pmatrix} 4 & 2 \\ 6 & 5 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 4x + 2y \\ 6x + 5y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$ <p>Set of invariant points is the line <math>y = -\frac{3}{2}x</math></p> | <p>M1</p> <p>A2</p><br><p>M1</p> <p>A1</p> | <p>5</p>   |
| (ii)  | $\begin{pmatrix} 4 & 2 \\ 6 & 5 \end{pmatrix} \begin{pmatrix} t \\ 2t - 3 \end{pmatrix} = \begin{pmatrix} 8t - 6 \\ 16t - 15 \end{pmatrix}$ <p><math>2(8t - 6) - 3 = 16t - 15,</math><br/>so the line <math>y = 2x - 3</math> is invariant</p>  | <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p>    | <p>Or finding images of <i>two</i> points on <math>y = 2x - 3</math><br/>Or images of two points correct<br/>Checking image(s) in <math>y' = 2x' - 3</math><br/>Or finding equation of image line</p> <p>4</p> |
| <p>OR The line <math>y = mx + c</math> is invariant if</p> $6x + 5(mx + c) = m[4x + 2(mx + c)] + c$ <p>which is satisfied by <math>m = 2, c = -3</math></p> |   | <p>M2</p> <p>A2</p>                        | <p>Properly shown</p>  |

|                      |   |  |   |
|----------------------|---|--|---|
| <p><b>(b)(i)</b></p> | $\begin{pmatrix} -1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} t \\ mt \end{pmatrix} = \begin{pmatrix} -t + 2mt \\ 3t + 4mt \end{pmatrix}$ <p>The line <math>y = mx</math> is invariant if</p> $3t + 4mt = m(-t + 2mt)$ $2m^2 - 5m - 3 = 0$ $(m - 3)(2m + 1) = 0$ $m = 3, -\frac{1}{2}$ <p>The other invariant line is <math>y = -\frac{1}{2}x</math></p> | <p>M1<br/>A1</p> <p>M1</p> <p>B1<br/>A1</p> <p>5</p> | <p>For LHS (or equivalent)</p> <p>For <math>m = 3</math>. Can be given for <math>\begin{pmatrix} -1 &amp; 2 \\ 3 &amp; 4 \end{pmatrix} \begin{pmatrix} 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 5 \\ 15 \end{pmatrix}</math>, also on <math>y = 3x</math></p> |
| <p><b>(ii)</b></p>   | $\begin{pmatrix} 5 & -1 \\ -8 & 2 \end{pmatrix} \begin{pmatrix} t \\ 3t \end{pmatrix} = \begin{pmatrix} 2t \\ -2t \end{pmatrix}$ <p>Equation of <math>L</math> is <math>y = -x</math></p>   | <p>M1<br/>A1</p> <p>2</p>                            | <p>Any one non-zero point on <math>y = 3x</math> is sufficient</p>  |
| <p><b>(iii)</b></p>  | <p>The line <math>y = 3x</math></p>   | <p>B1</p> <p>1</p>                                   |   |
| <p><b>(iv)</b></p>   | $Q = P^{-1} = \frac{1}{2} \begin{pmatrix} 2 & 1 \\ 8 & 5 \end{pmatrix}$   | <p>B1B1</p> <p>2</p>                                 | <p>For <math>\frac{1}{2}</math> and <math>\begin{pmatrix} 2 &amp; 1 \\ 8 &amp; 5 \end{pmatrix}</math></p>   |
| <p><b>(v)</b></p>    | <p><b>Q</b> transforms <math>L</math> to <math>y = 3x</math><br/> <b>M</b> transforms <math>y = 3x</math> to <math>y = 3x</math><br/> <b>P</b> transforms <math>y = 3x</math> to <math>L</math><br/>                 Hence <b>R</b> transforms <math>L</math> to <math>L</math></p>   | <p>M1<br/>A1</p> <p>2</p>                            | <p>Considering at least two successive transformations of <math>L</math></p>  |
|                      | <p>OR, if done after (vi),</p> $\begin{pmatrix} 16 & 11 \\ -18 & -13 \end{pmatrix} \begin{pmatrix} t \\ -t \end{pmatrix} = \begin{pmatrix} 5t \\ -5t \end{pmatrix}$ <p>which is also on <math>L</math></p>  | <p>M1<br/>A1</p>                                     |   |
| <p><b>(vi)</b></p>   | $R = PMQ = \begin{pmatrix} 5 & -1 \\ -8 & 2 \end{pmatrix} \begin{pmatrix} -1 & 2 \\ 3 & 4 \end{pmatrix} \frac{1}{2} \begin{pmatrix} 2 & 1 \\ 8 & 5 \end{pmatrix}$ $= \begin{pmatrix} 16 & 11 \\ -18 & -13 \end{pmatrix}$  | <p>M1A1 ft<br/>A1 cao</p> <p>3</p>                   | <p>Give M1A0 if order wrong</p>   |